

Chapter 11. A Voice-Synthesizer Project

This chapter is the extension of the previous chapter so that we generate voice from the typed words from the keyboard, using a voice synthesizer board. Imagine that a person communicate in a written form and wants it to be spoken. So the person can see what is s typed and the party can hear what the person intends to say. This feature needs a voice synthesizer which does the text-to-voice conversion.

1. DoubleTalk RC8650 Voice Synthesizer

The DoubleTalk RC8650 is versatile voice and sound synthesizers, integrating a sophisticated text-to-speech processor, audio recording and playback, musical and sinusoidal tone generators, telephone dialer and A/D converter, all in easy to use chipsets. This chipset translate plain English text into speech in real time, without the assistance of a PC or high-powered processor. It enables us to add text-to-speech capability to virtually any design, quickly and painlessly.

In addition, integrated tone generators provide telephone dialing, music, and programmable signaling tones. Up to 3.5 MB of built in, flash-based recording memory can store up to 15 minutes of sound files, which can be played back on demand by the host.

The RC8650 chip set is comprised of two surface-mounted devices: the RC8650 and RC4651. Both operate from a +5 V supply and consume very little power. In many cases, all that is needed to build a fully functional system is a low pass filter and audio amplifier (which can often be combined into the same circuit).

As text messages are sent to the RC8650, the RC8650 automatically converts the messages into speech using an integrated text-to-speech processor. The TTS processor utilizes RC Systems' DoubleTalk TTS technology, which is based on a patented voice concatenation technique using real human voice samples. Voice control parameters, such as speed, volume, tone, pitch and expression, can also be embedded within the text stream for dynamic on-the-fly voice control. RS-232 compatible serial and 8 bit bus interfaces are included to allow the chipset to interface to virtually any CPU or microcontroller.

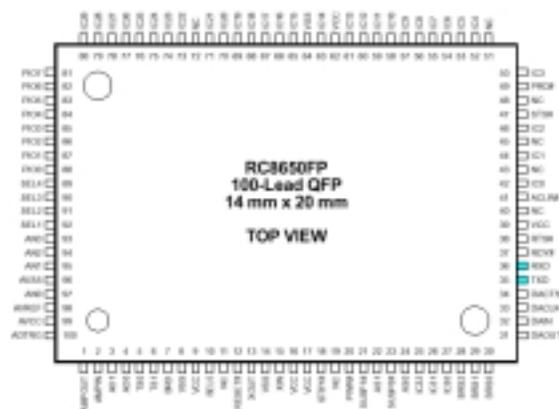


Fig. 79 RC8650FP

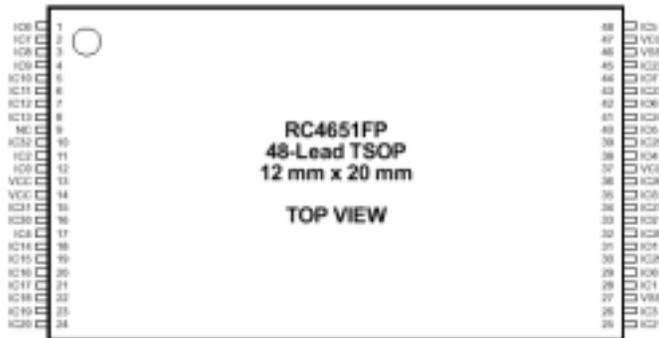


Fig. 80 RC4651FP

The DoubleTalk RC8650 Evaluation Kit enables you to experiment with the RC Systems RC8650 voice synthesizer chip set. Included in the kit are:

- Evaluation board containing the RC8650 chip set
- Speaker with volume control
- Serial cable
- RC8650 Studio software

The evaluation board is a complete, versatile voice synthesizer which can be used with the RC8650 Studio software as well as in stand-alone applications. The board includes the RC8650 voice synthesizer chip set, audio power amplifier, voltage regulator, RS-232C interface, and parallel I/O port. The chip set's I/O lines are made accessible through header connectors near the edge of the board. SW1 in the evaluation board is the Reset switch. Press once when we meet some problem.

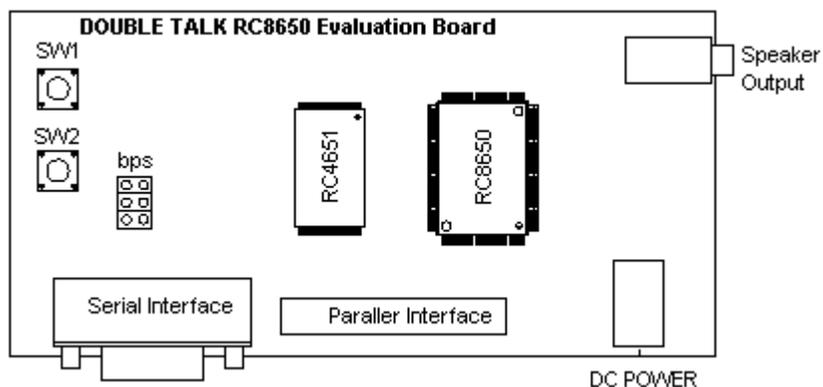


Fig. 81 RC8650 Evaluation board

The RC8650 Studio software is NOT required, however, in order to use the evaluation board. The board can be used "stand-alone" if desired by simply printing the desired text and commands to it via the board's serial or parallel ports.

So we directly tap the RXD and TXD pin of RC8650 chip set for direct serial communication with 16F877 without passing through RS-232 level converter such as MAX232. In this stand-alone application, a text word typed is voiced after a CR key is provided to RC8650 voice synthesizer.

2. Operating Modes of RC8650 Chip Set

The RC8650 has six primary operating modes and two low-power modes designed to achieve maximum functionality and flexibility. The operating mode can be changed anytime, even on the fly. Note The RC8650 does not make any distinction between uppercase and lowercase characters. Text and commands may be sent as all uppercase, all lowercase, or any combination thereof.

Text mode. In this mode, all text sent to the RC8650 is spoken as complete sentences. Punctuation is also taken into consideration by the intonation generation algorithms. The RC8650 will not begin speaking until it receives a CR (ASCII 13) or Null (ASCII 00) character—this ensures that sentence boundaries receive the proper inflection. This is the default operating mode.

Character mode. This mode causes the RC8650 to translate input text on a character-by-character basis; i.e., text will be spelled instead of spoken as words. The RC8650 does not wait for a CR/Null in this mode.

Phoneme mode. This mode disables the RC8650's text-to-phonetics translator, allowing the RC8650's phonemes to be directly accessed. Phonemes in the input buffer will not be spoken until a CR or Null is received.

Real Time Audio Playback mode. In this mode, data sent to the RC8650 is written directly to its audio buffer. This results in a high data rate, but provides the capability of producing the highest quality speech, as well as sound effects. PCM and ADPCM data types are supported.

Prerecorded Audio Playback mode. This mode allows recorded speech and sound effects to be stored on-chip and played back at a later time. PCM and ADPCM data types are supported.

Tone Generator modes. These modes activate the RC8650's musical tone generator, sinusoidal generator, or DTMF generator. They can be used to generate audible prompts, music, signaling tones, dial a telephone, etc.

Idle mode. To help conserve power in battery-powered systems, the RC8650 automatically enters a reduced-power state whenever it is inactive. Data can still be read and written to the RC8650 while in this mode. Current draw in this mode is typically 1 mA.

Standby mode. This mode powers down the RC8650, where current draw is typically only 2 μ A. Standby mode can be invoked from either the STBY# pin or with the Sleep command. Data cannot be read from or written to the RC8650 in this mode.

3. Commands of RC8650

The commands described in the following pages provide a simple yet flexible means of controlling the RC8650 under software control. They can be used to vary voice attributes, such as the volume or pitch, to suit the requirements of a particular application or listener's preferences. Commands are also used to change operating modes. Commands can be freely intermixed with the text that is to be spoken, allowing the voice to be dynamically controlled. Commands affect only the data that follows them in the data stream.

The command character. The default RC8650 command character is Control-A (ASCII 01). The command character itself can be spoken by the RC8650 by sending it twice in a row: Control-A Control-A. This special command allows the command character to be spoken without affecting the operation of the RC8650, and without having to change to another command character and then back again.

Command Syntax. All RC8650 commands are composed of the command character, a parameter *n* comprised of a one to three-digit number string, and a single string literal that uniquely identifies the command. Some commands simply enable or disable a feature of the RC8650 and do not require a parameter. The general command format is:

<command character>[<number string>]<string literal>

If two or more commands are to be used together, each must be prefaced with the command character. This is the only way the RC8650 knows to treat the remaining characters as a command, rather than text that should be spoken. For example, the following commands program pitch level 40 and volume level 7 (Control-A is the default command character):

```
Control-A "40P" Control-A "7V"
```

4. Some Global Commands of RC8650

Voice (nO). The text-to-speech synthesizer has eight standard voices and a number of individual voice controls that can be used to independently vary the voice characteristics. Voices are selected with the commands 0O through 7O, shown in Table 2.3. Because this command alters numerous internal voice parameters (pitch, expression, tone, etc.), it should precede any individual voice control commands.

n	Voice Name
0	Perfect Paul(default)
1	Vader
2	Big Bob
3	Precise Pete
4	Ricochet Randy
5	Biff
6	Skip
7	Robo Robert

Volume (nV). This is a global command which controls the RC8650's output volume level, from 0V through 9V. 0V yields the lowest possible volume; maximum volume is attained at 9V. The default volume is 5V. The Volume command can be used to set a new listening level, create emphasis in speech, or change the output level of the tone generators.

DTMF Generator (n*). The DTMF (Touch-Tone) generator generates the 16 standard tone pairs commonly used in telephone systems. Each tone pair generated by the RC8650 is 100 ms in duration, more than satisfying the telephone signaling requirements (this can be extended to 500 ms with the Protocol Options Register command). The mapping of the command parameter n to the buttons on a telephone is shown below. The "pause" tone is used to generate the inter-digit delay in phone number strings. The generator's output level can be adjusted with the Volume command (nV). DTMF commands are buffered, and may be intermixed with text and other commands without restriction.

n	Button
0	0
-	-
-	-
9	9
10	*
11	#
12	A
13	B
14	C
15	D
16	pause

5. Coding Example for RC8650

As mentioned above we tap the RXD (pin#35) and TXD (pin# 36) of RC8650 chip for serial communication with 16F877. Since we need the hardware implemented serial communication and the MAX232 for hex code download from the PC we work for coding, we utilize the software implemented serial communication (refer to Chapter 6) for the connection with RC8650, and we pick RD5 and RD4 for RX and TX pins for 16F877, respectively.

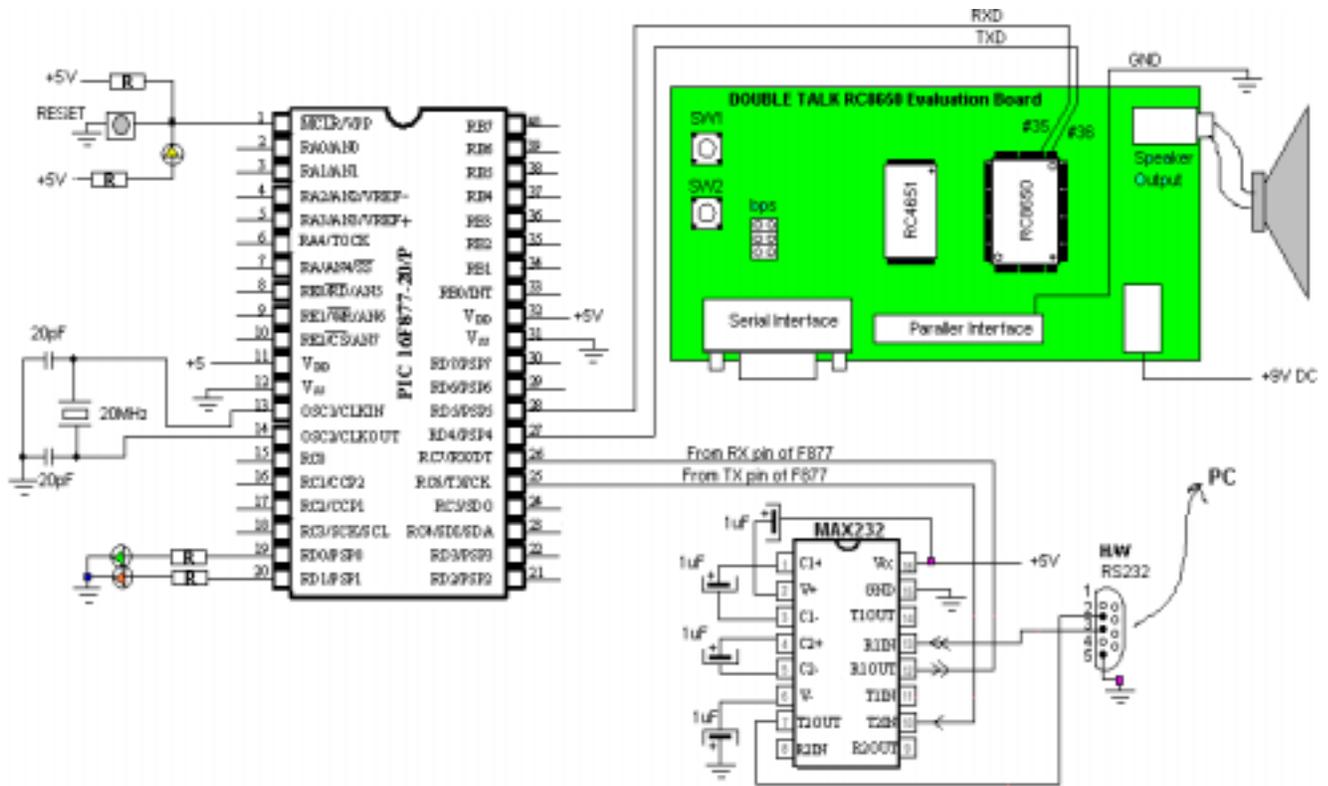


Fig. 82 RC8650 connection to PIC 16F877

The example code is to simply dial a number and generate the voice for a text of "I LOVE YOU." We will test all 8 different voices supported by the chip set and control volume of the voice.

First we can set the volume to 4 by the following routine. Since every command should start with the command character Control-A, we start with it and use the global command format for volume. Note that every command and attribute is entered as character. CTRLA is declared as 0x01 ASCII code. Subroutine TXSW is 19200 bps software generated serial communication (transmission) routine that we already discussed in Chapter 6.

```

;
    movlw    CTRLA
    call    TXSW
    movlw    '4'
    call    TXSW
    movlw    'V'
    call    TXSW           ;Send CTRL-A > 4 > V
    
```

For voice, we want to apply all 8 different voices, so we first assign 0 to a register, VOICE, and increase by 1 after we generate the sound of the text "I Love You". By the way, the default operational mode of RC8650 chip set is the text-mode which converts text to voice.

The phone dialing precedes the "I Love You" message. The phone dialing, or DTMF generation, is done by the following order of command and each digit of phone number:

CTRL-A > Digit_1>*>CTRL-A>Digit_2>*CTRL-A>Digit_n>*.

In other words, the CTRL-A should come before the number and it should be followed by the star (*) mark.

The following instructions dial and generate DTMF of the author's office number:202-806-4821 with preceding '1' for long distance call indication.

```

movlw    CTRLA
call     TXSW
movlw    '1'
call     TXSW
movlw    '*'
call     TXSW

```

```

movlw    CTRLA
call     TXSW
movlw    '2'
call     TXSW
movlw    '*'
call     TXSW

```

```

movlw    CTRLA
call     TXSW
movlw    '0'
call     TXSW
movlw    '*'
call     TXSW

```

```

movlw    CTRLA
call     TXSW
movlw    '2'
call     TXSW
movlw    TXSW

```

```

movlw    CTRLA
call     TXSW
movlw    '8'
call     TXSW
movlw    '*'
call     TXSW

```

```

movlw    CTRLA
call     TXSW
movlw    '0'
call     TXSW
movlw    '*'
call     TXSW

```

```

movlw    CTRLA

```

```

call    TXSW
movlw   '6'
call    TXSW
movlw   '*'
call    TXSW

movlw   CTRLA
call    TXSW
movlw   '4'
call    TXSW
movlw   '*'
call    TXSW

movlw   CTRLA
call    TXSW
movlw   '8'
call    TXSW
movlw   '*'
call    TXSW

movlw   CTRLA
call    TXSW
movlw   '2'
call    TXSW
movlw   '*'
call    TXSW

movlw   CTRLA
call    TXSW
movlw   '1'
call    TXSW
movlw   '*'
call    TXSW

```

This long lines of the code can be simplified by developing a subroutine and a table. First, let's make a table for the phone number:

```

;=== Phone Number Table=
PhoneTable
    movf   PHONEdigit,0
    addwf  PCL                ;PC+0
    DT     "12028064821"     ;11 numbers
    retlw  0

```

As we see above it looks very clean and simple with table format. Now let's have a dialing subroutine which dials the numbers stored in the PhoneTable table. In the Dialing subroutine, the PhoneTable is called 11 times, and at each time, with PC increased, the next number is restored to W register for writing to RC8650. The command CTRL-A and star mark (*) are wrapping the phone number for DTMF generation.

```

Dialing    movlw    0x0B        ;11 phone digits
           movwf    Ptemp
           clrf     PHONEdigit
Dagain    movlw    CTRLA
           call     TXSW
           call     PhoneTable    ;get the number
           call     TXSW
           movlw    '*'
           call     TXSW
           incf    PHONEdigit
           decfsz  Ptemp
           goto    Dagain
           return

```

The burst duration of the DTMF is 100ms in the default setting of the chip set. We can change the duration to 500ms by changing the content of Protocol Options Register of the chip set. Details on this subject is left to the readers, and here goes the command for 500ms burst duration:

CTRL-A >"1">"6">"0">"G".

Selection of a voice comes with CTRL-A followed by the voice number, 0 through 7, and the letter O, as shown below

```

movlw     CTRLA
call      TXSW
movf      VOICE,0        ;write the VOICE
call      TXSW
movlw     'O'
call      TXSW

```

Since the text mode is the default mode of RC8650, write a message is pretty simple. For "I Love You! " message, we go like this:

```

movlw     'I'
call      TXSW
movlw     ' '           ;space
call      TXSW
movlw     'L'
call      TXSW
movlw     'o'
call      TXSW
movlw     'v'
call      TXSW
movlw     'e'
call      TXSW
movlw     ' '           ;space
call      TXSW
movlw     'Y'
call      TXSW
movlw     'o'
call      TXSW
movlw     'u'

```

```

call    TXSW
movlw   'I'
call    TXSW

```

As we did in phone number, the text message can also be simplified by a subroutine and a table. First, the message table looks like this:

```

MessageTable
  movf   MESSAGEdigit,0
  addwf  PCL
  DT     "I LOVE YOU!"    ;11 texts
  retlw  0

```

And the subroutine for text message writing goes as shown below. There are 11 character readings and writings without any other commands and command characters. When all characters in the text message are read, then CR is written to RC8650 to signal the end of the text message and to request for conversion to voice.

```

;Subroutine Message
Message
  movlw   0x0B           ;11 characters
  movwf   Mtemp
  clrf    MESSAGEdigit
Magain
  call    MessageTable   ;read a text
  call    TXSW
  incf    MESSAGEdigit
  decfsz  Mtemp
  goto    Magain
  movlw   0x0D
  call    TXSW           ;CR key for voicing after 11 readings
  return

```

Since this is the first incidence of RC8650 voice synthesizer application, the following code lists the full program. When you run this, you would hear very quick digital dialing sound from the speaker (100ms per each digit) followed by a voice saying "I Love You." This dialing and message repeats for 8 different voices.

```

;RC8650.asm
;
;TABLE IS USED TO SIMPLIFY THE PROGRAM
; FOR PHONE NUMBER
;AND
;TEXT MESSAGE
;
;This program is to:
; 1. test the RCS8650 voice synthesizer evaluation board
; 2. Send ASCII word followed by CR key
; 3. Then the sound must be generated from the speaker attached to the board
; 4. Connection
;   DB9 of 16F877 to DB9 of RC6850 Board
;
; This connection is made without using MAX232 chips at both sides

```

```

;Direct connection between 16F877 and RC8650

; Baud rate for this is set as 19200
;
;This program is asynchronous communication using software method
;
;F = 20 MHz
;B = Baud Rate
;For B=19200, one Baud cycle (BC) is about 52uS
;
;
;TRANSMIT MODE
;First START bit is sent by setting the TX pin to LOW for (BC) seconds
;And, from then on, the TX Pin is Set/Cleared corresponding to the data bit
;every (BC) seconds.
;8N1 format
;
;TX Pin = RD4
;RX Pin = RD5
;
;Terminal set up: 8N1 19200
;
;

```

```
list P = 16F877
```

```

PCL      EQU    0x02
STATUS  EQU    0x03
CARRY    EQU    0x00
TRISD    EQU    0x88
PORTD    EQU    0x08
TXPIN    EQU    0x04      ;RD4
RXPIN    EQU    0x05      ;RD5
MSB      EQU    0x07
CTRLA    EQU    0x01      ;RC8650 Command Character
;
;note

```

```
;RAM for DELAY SUBROUTINE
```

```

CBLOCK   0x20      ; RAM AREA for USE at address 20h
    PHONEdigit
    Ptemp
    MESSAGEdigit
    Mtemp
    VOICE
    Kount52us
    Kount100us
    Kount10ms
    Kount100ms
    Kount1s
    RCSreg          ;data to RCS's RC8650
    Bitcount        ;data bit count
    Kount           ;Delay count (number of instr cycles for delay)
ENDC

```

```
;=====
```

```

        org          0x0000          ;line 1
        GOTO        START          ;line 2 ($0000)
;=====
        org          0x05

START

        banksel    TRISD
; Port setting (1 for input and 0 for output)
; 1110 0000

        movlw      0xE0
        movwf      TRISD
        banksel    PORTD
        bcf        PORTD,0x00
        bcf        PORTD,0x01

;RD4 - TXPin (out)  RD5 - RXPin (in)

;TEXT MODE is DEFAULT MODE

;Default mode of RC8650 is Text mode
;So keep this
;Change the volume by nV command
;n = [0,9] with 5 as default
;Change to 4
        movlw      CTRLA
        call       TXSW
        movlw      '4'
        call       TXSW
        movlw      'V'
        call       TXSW

        movlw      0x30
        movwf      VOICE          ;starting from 0

BEGIN
        banksel    RCSreg
        clrf       RCSreg
;Change the Voice to n0 command
;0 for Perfect Paul (Default)
;1 for Vader
;2 for Big Bob
;3 for Precise Pete
;4 for Ricochet Randy
;5 for Biff
;6 for Skip
;7 for Robo Robert
;
;Apply all 8 voices one at a time
        movlw      CTRLA
        call       TXSW
        movf       VOICE,0          ;write the VOICE
        call       TXSW
        movlw      'O'

```

```

    call    TXSW
;

    call    Dialing
    call    delay1s
    call    delay1s

;Text Message

    call    Message
    call    delay1s
    call    delay1s

;next voice
    incf    VOICE
    btfss   VOICE,0x03    ;third bit =1 means VOICE=8
    goto    BEGIN
    movlw   0x30
    movwf   VOICE        ;again with 0
    call    delay1s
    call    delay1s
    goto    BEGIN

;=== Phone Number Table=
PhoneTable
    movf    PHONEdigit,0
    addwf   PCL

    DT      "12028064821"    ;PC+0
    retlw   0                ;11 numbers
;
MessageTable
    movf    MESSAGEdigit,0
    addwf   PCL

    DT      "I LOVE YOU!"    ;11 texts
    retlw   0
;
;Subroutine Dialing

;DTMF Generation (command is n*)
;Call the following Number
;1-202-806-4821
;DTMPF usual (default) burst duration is 100ms
;this could become 500ms by changing the Protocol Options Register
;by nG command
; CTRLA>"1">"6">"0">"G" would change it to 500ms
;Fro details see the RC8650 data sheet
Dialing
    movlw   0x0B            ;11 phone digits
    movwf   Ptemp
    clrf    PHONEdigit
Dagain
    movlw   CTRLA
    call    TXSW
    call    PhoneTable

```

```

        call    TXSW
        movlw   '*'
        call    TXSW
        incf    PHONEdigit
        decfsz  Ptemp
        goto    Dagain
        return

;
;Subroutine Message
Message
        movlw   0x0B           ;11 characters
        movwf   Mtemp
        clrf    MESSAGEdigit
Magain
        call    MessageTable
        call    TXSW
        incf    MESSAGEdigit
        decfsz  Mtemp
        goto    Magain
        movlw   0x0D
        call    TXSW           ;CR key for voicing
        return

;Software TX routine
;The data to be sent is stored in W
TXSW
        banksel RCSreg
        movwf   RCSreg
        movlw   0x08           ;8 ---->W
        movwf   Bitcount      ;8 data bits

;send a START bit
        bcf     PORTD, TXPin
;delay for 1*(BC) cycles
        call    Delay52us      ;Keep this!
TXNEXT
        bcf     STATUS, CARRY
        rrf     RCSreg          ;LSB first mode (normal)
        btfsc   STATUS,CARRY
        bsf     PORTD, TXPin
        btfss   STATUS,CARRY
        bcf     PORTD, TXPin
        call    Delay52us
        decfsz  Bitcount
        goto    TXNEXT
;send STOP bit
        bsf     PORTD, TXPin
        call    Delay52us      ;
;wait until the end of STOP bit
        return

;
;====SUBROUTINES =====
;delay 52us for one baud cycle of 19200 bps
Delay52us
        movlw   0x54

```

```

        movwf      Kount52us
R52us  decfsz     Kount52us
        goto      R52us
        return

;=====
;DELAY SUBROUTINES
;
;
;100us delay needs 500 instruction cycles
; 500 =166*3 +2 ---->Kount=166=0xA6
; or  =165*3 +5 ---->Kount=165=0xA5
; or  =164*3 +8 ---->Kount=164=0xA4
Delay100us
        banksel   Kount100us
        movlw     H'A4'
        movwf     Kount100us
R100us
        decfsz    Kount100us
        goto      R100us
        return

;
;10ms delay
; call 100 times of 100 us delay (with some time discrepancy)
Delay10ms
        banksel   Kount10ms
        movlw     H'64' ;100
        movwf     Kount10ms
R10ms  call      delay100us
        decfsz    Kount10ms
        goto      R10ms
        return

;
;1 sec delay
;call 100 times of 10ms delay
Delay1s
        banksel   Kount1s
        movlw     H'64'
        movwf     Kount1s
R1s    call      Delay10ms
        decfsz    Kount1s
        goto      R1s
        return

;
;END OF CODE
        END

```

3. Coding for a Complete System of Voice Synthesizer, LCD, and Keyboard

Now, it's about time to connect the keyboard, the LCD module, and the RC8650 evaluation system for the final version of this application. Our scheme here is that the keyed characters are displayed to the LCD module and that the texts are pronounced as text message when CR key is entered. As we know, the CR key also moves the cursor to the first position of the next line of

the current cursor position. The schematic for the connections and pin assignments are as shown below.

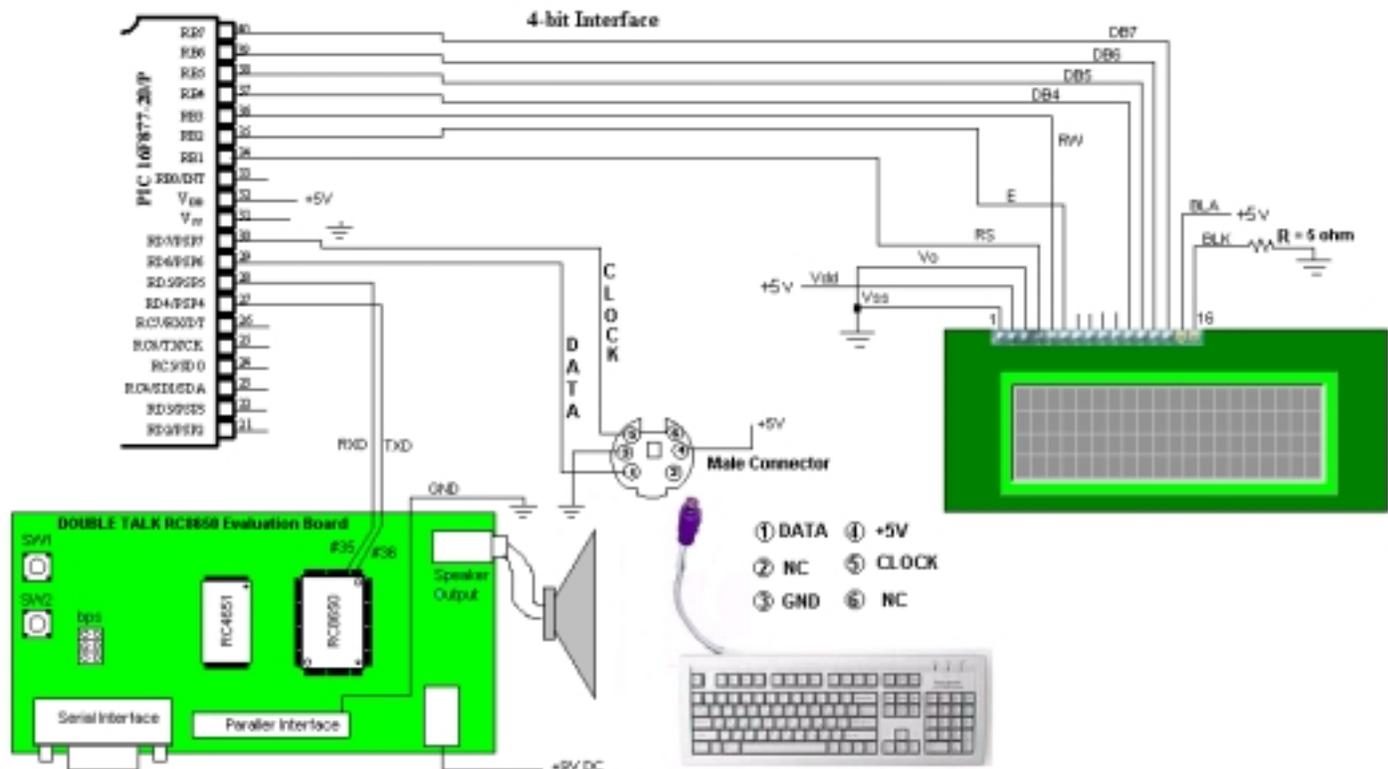


Fig. 83 Keyboard and LCD module connection to RC8650 evaluation system

Before we examine an example code for this final version, let's consider some new stuffs we bring to the project compared with the previous version. First, we have to have a storage space to store texts so that, when CR is pressed, we retrieve them and write to the RC8650 chip set for text-to-voice conversion. Second, we have to accommodate the BS key. When BS key is pressed, we have to not only move the cursor on LCD module to move back by one space but also change the stored text so that the keys after the BS overrides the text previously entered in to a storage location.

Let's discuss about saving the entered characters. Since we have general purpose register spaces in Bank 1 (Bank 0 spaces are usually occupied by the variables defined in the program.) of the RAM, we will going to use the first 80 bytes of the free space in Bank 1. Since we have 4x20 (total of 80 characters), the first 80 spaces, starting from address A0h, completely fit to our purpose. For this allocation, we will use an indirect addressing mode by using INDF and FSR registers. INDF register is the indirect file register to hold a byte data and FSR is the file register selection register. The content of FSR is the address of INDF. INDF is not a physical register and FSR is the address pointer for INDF. In other words, if FSR contains A0h, and if you have the following instruction:

```
movlw    'A'
movwf    INDF
```

Then, the hex number 41h (for 'A') would be written to the address A0h indicated by FSR. If you want to write 'B' at the address A1h, you increase FSR by 1 and write it to INDF:

```

incf      FSR
movlw    'B'
movwf    INDF

```

So, as we see here, there is no direct contact or control with INDF register, instead, they are performed via FSR.

In example code, we store any character to the storage space starting at A0h until we receive a CR key. When CR is entered, we send the whole text to RC8650 chip set followed by CR (which triggers the text to voice conversion). After the conversion, we move the FSR to the original A0h address so that the next can be overwritten.

So, whenever a text (other than CR or BS) is entered, it is interpreted to ASCII character using the table of NoShiftKeyTable, ShiftKeyTable, or CAPKeyTable, depending upon the pressing of Shift or Caps Lock key, or not. Then, it is displayed on the LCD module, and at the same time, the storage address for the text is increased by 1 and the count for number of texts entered is also increased by 1. The variable Nchar in the instruction below monitors the number of texts stored for the voice conversion.

An example code when no Shift or Caps Lock key is pressed.

```

call      NoShiftKeyTable      ;(X) display
movwf    INDF                  ;store the character at INDF
incf     FSR
incf     Nchar
call     LCDisplay

```

An example code when Caps Lock key is pressed.

```

call      CAPKeyTable
movwf    INDF                  ;store the character at INDF
incf     FSR
incf     Nchar
call     LCDisplay

```

The subroutine for converting the stored texts into voice is shown below. The subroutine VoiceText changes the RC8650 mode to text mode (this is not required since the default mode is the text mode), then write the stored texts as numbered by the content of Nchar in the software implemented, asynchronous serial communication routine TXSW. After writing all the texts stored, it then sends CR to trigger the RC8650 to convert the texts to voice. Once the job is done, it moves the storage starting address to A0h.

```

;subroutine
VoiceText
;if Nchar=0 return (nothing to display)
movlw    CTRLA
call     TXSW
movlw    'T'
call     TXSW      ;text mode

```

```

        banksel    Nchar
        movf      Nchar,0
        clrf     STATUS
        xorlw    0x00
        btfsc   STATUS,ZERO
        return
        movlw   0xA0
        movwf  FSR
NextChar
        movf   INDF,0
        call  TXSW
        decfsz Nchar
        goto  domore
        movlw 0x0D      ;voice ON
        call  TXSW
        movlw 0xA0
        movwf FSR
        return
DMore
        incf   FSR
        goto  NextChar

```

When BS key is entered, the address pointer for the text must be decreased by 1 and the number of texts must be also decreased by 1:

```

        decf   FSR
        decf   Nchar

```

Even though we discussed in detail about the LCD display of the keyboard keys, since this final version involves very important part of voice conversion, the following code lists the full program for the connection of a AT or PS/2 type keyboard, an 20x4 LCD module with 4-bit interfacing scheme, and a voice synthesizer chip set of RC8650. Check for the changes in the PCLATH related instruction at the tables.

```

;kbd6.asm
;
;kbd-LCD-Voice Synthesizer connection
;CR key will start the text-voice conversion
;
;texts typed are stored at the RAM space (bank 1) starting @A0
;using FSR pointer and INDF register
;FSR directs the INDF register
;When CR is entered, then the text-voice routine is called
;to make sounds.
;
; Baud rate for this is set as 19200 for SW enabled Serial Communication
; to RC8650 Chip Set
;
;This program is asynchronous communication using software method

```

```

;
;F = 20 MHz
;B = Baud Rate
;For B=19200, one Baud cycle (BC) is about 52uS
;
;
;TRANSMIT MODE
;First START bit is sent by setting the TX pin to LOW for (BC) seconds
;And, from then on, the TX Pin is Set/Cleared corresponding to the data bit
;every (BC) seconds.
;8N1 format
;
;TX Pin = RD4
;RX Pin = RD5
;
; LCD is with 4-bit interfacing
;
;CR key would change the line
;
; Pin Connection from LCD to 16F877
; LCD (pin#)      16F877 (pin#)
;DB7 (14) -----RB7(40)
;DB6 (13) -----RB6(39)
;DB5 (12) -----RB5(38)
;DB4 (11) -----RB4(37)
;E (6)  -----RB2(35)
;RW (5)  -----RB3(36)
;RS (4)  -----RB1(24)
;Vo (3)  -----GND
;Vdd (2) -----+5V
;Vss (1) -----GND
;
;KEYBOARD Interfacing
;CLOCK -----RD7 (input)
;DATA -----RD6 (input)
;
;==RC8650 pin connection ==
;RD4 - TXPin (out)
;RD5 - RXPin (in)

        list P = 16F877
INDF      EQU    0x00      ;indirect register
FSR       EQU    0x04      ;Pinter of INDF
STATUS    EQU    0x03
PCL       EQU    0x02      ;For Key Table Calling
PCLATH    EQU    0x0A      ;upper part of PC
CARRY     EQU    0x00
BORROW    EQU    0x00
ZERO      EQU    0x02
PORTB     EQU    0x06
TRISB     EQU    0x86
RS        EQU    0x01      ;RB1
E         EQU    0x02      ;RB2
RW        EQU    0x03      ;RB3
TRISD     EQU    0x88
PORTD     EQU    0x08
CARRY     EQU    0x00

```

```

MSB      EQU    0x07
CLOCK    EQU    0x07      ;from Keyboard (RD7)
KDATA    EQU    0x06      ;from Keyboard (RD6)
TXPIN    EQU    0x04      ;to RC8650
RXPIN    EQU    0x05      ;RD5
MSB      EQU    0x07
CTRLA    EQU    0x01      ;RC8650 Command Character

;RAM Area

        CBLOCK    0x20
            RCSreg          ;RC8650
            VOICE
;
            CURSOR          ;tracking the current display position
;CURSOR (tracking purpose) (Decimal)
;1  2  3  4  5  6  7  8  9 10 11 12 13 14 15 16 17 18 19 20  line1
;21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40  line 2
;41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60  line 3
;61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80  line 4
;
;DDADDR CONTENT read from LCD Module (HEX)
;00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F 10 11 12 13  line1
;40 41 42 43 44 45 46 47 48 49 4A 4B 4C 4D 4E 4F 50 51 52 53  line 2
;14 15 16 17 18 19 1A 1B 1C 1D 1E 1F 20 21 22 23 24 25 26 27  line 3
;54 55 56 57 58 59 5A 5B 5C 5D 5E 5F 60 61 62 63 64 65 66 67  line 3

            DDaddr          ;Display address (cursor pos)
            DDtemp1
            DDtemp2
            Nchar

            Dkey            ;Key character to be displayed
            DATAreg
            Bitcount
            Kstat
            Kount52us
            Kount120us     ;Delay count (number of instr cycles for delay)
            Kount100us
            Kount1ms
            Kount10ms
            Kount100ms
            Kount1s
            Kount10s
            Kount1m
            Temp            ;temp storage
        ENDC

;program should start from 0005h
;0004h is allocated to interrupt handler

        org      0x0000
        goto    START

        org      0x05

```

Start

```

    banksel    TRISD
; 1100 0000

    movlw     B'11100000' ;Rd7 for CLOCK and Rd6 for DATA as inputs
                                ;rd5 as RX from RC8600
                                ;rd4 as TX to RC8600
    movwf     TRISD

    call      delay1s           ;Give Keyboard to send STATUS to the host

    BANKSEL   TRISB
    movlw     0x00
    movwf     TRISB           ;All output

    banksel   PORTB
    clrf      PORTB           ;RW set LOW here

    clrf      CURSOR           ;Current Display Location
    incf      CURSOR           ;Home cursor position (1, 1)
;LCD routine starts
    call      delay10ms
    call      delay10ms

    banksel   PORTB
    clrf      PORTB           ;RW set LOW here
                                ;give LCD module to reset automatically
    call      LCD4INIT

;END OF LCD INITIALIZATION
;RC8600 setup
;TEXT MODE is DEFAULT MODE

;Default mode of RC8650 is Text mode
;So keep this
;Change the volume by nV command
;n = [0,9] with 5 as default
;Change to 6
    movlw     CTRLA
    call      TXSW
    movlw     '6'
    call      TXSW
    movlw     'V'
    call      TXSW
;VOICE TYPE SELECTION
;Change the Voice to n0 command
;0 for Perfect Paul (Default)
;1 for Vader
;2 for Big Bob
;3 for Precise Pete
;4 for Ricochet Randy
;5 for Biff
;6 for Skip
;7 for Robo Robert

    movlw     CTRLA

```

```

        call        TXSW
        movwf      '1'           ;perfect Paul
        call        TXSW
        movlw      '0'
        call        TXSW
;
        movlw      0xA0
        movwf      FSR           ;data pointer @A0 in Bank 1
;receiving data
        banksel    Nchar
        clrf       NCHAR         ;number of data entered
;=====
;KBD Monitoring
BEGIN

        banksel    DATAreg
        clrf       DATAreg
        clrf       DDADDR        ;DD RAM ADDRESS READ from LCD
;
; CHECK IF THE CLOCK is HIGH at least for 10mS

        banksel    PORTD
        btfss     PORTD, CLOCK
        goto       BEGIN         ;if CLOCK is LOW, start again
        call       Delay10ms     ;10mS delays

;check again for CLCOK
        btfss     PORTD, CLOCK
        goto       BEGIN
;READY FOR CLOCK PULSES

        clrf      KSTAT
KEYIN
;X reading
        call      RX11bit        ;
        clrf      STATUS
        movf      DATAreg,0     ;Break Code?
        xorlw     0xF0
        btfss    STATUS,ZERO
        goto     CAT
;BREAK is detected. Abort It. Resume It
        goto     BEGIN
;Category detection
CAT    clrf      STATUS
        movf      DATAreg,0
        xorlw     0xE0
        btfsc    STATUS,ZERO
        goto     Begin          ;E0 keys (CAT2) are ignored
        clrf      STATUS
        movf      DATAreg,0
        xorlw     0x12
        btfsc    STATUS,ZERO
        goto     LRSHIFT
        clrf      STATUS
        movf      DATAreg,0
        xorlw     0x59
        btfsc    STATUS,ZERO

```

```

goto      LRSHIFT
clrf      STATUS
movf      DATAreg,0
xorlw     0x58          ;CAPS LOCK
btfsc    STATUS,ZERO
goto      CAPS
movf      DATAreg,0
clrf      STATUS          ;CR check
xorlw     0x5A
btfsc    STATUS,ZERO
goto      CRhandle
movf      DATAreg,0
clrf      STATUS
xorlw     0x66
btfsc    STATUS,ZERO
goto      BShandle      ;Back Space Handling
                                ;L Shift ==>12 | F0 12
                                ;R Shift ==>59 | F0 59
;CAT1 has the format of (X)|(F0)(X)
CAT1 movf DATAreg,0
;check if the key in is CR
;Then we have to move the next line

        call      NoShiftKeyTable      ;(X) display
movwf    INDF          ;store the character at INDF
incf    FSR
incf    Nchar
call    LCDisplay
;(F0) detection
call    RX11bit
clrf    STATUS
movf    DATAreg,0
xorlw   0xF0
btfss  STATUS,ZERO
;Key is not broken. Still pressed,
goto    CAT1
;Key is broken
;Last (X) reading
call    RX11bit          ;(X) after F0

goto    BEGIN

;L-SHIFT and R-SHIFT has the form
;L-SHIFT and a character 12 X | F0 X |F0 12
;R-SHIFT and a character 59 X | F0 X |F0 59

LRSHIFT          ;12 or 59 entered

;(F0) detection
call    RX11bit
clrf    STATUS
movf    DATAreg,0
xorlw   0xF0
btfsc  STATUS,ZERO
goto    BEGIN

```

;X

```

    clrf        STATUS                ;if (12) do not display
    movf       DATAreg,0
    xorlw     0x12
    btfsc    STATUS, ZERO
    goto     LRSHIFT

    clrf        STATUS                ;if (59) do not display
    movf       DATAreg,0
    xorlw     0x59
    btfsc    STATUS, ZERO
    goto     LRSHIFT

                                ;a Key (X) is entered
    movf       DATAreg,0
    call      ShiftKeyTable
    movwf     INDF                    ;store the character at INDF
    incf     FSR
    incf     Nchar
    call     LCDisplay

;(F0) detection
    call      RX11bit
    clrf     STATUS
    movf     DATAreg,0
    xorlw   0xF0
    btfss   STATUS,ZERO
    goto    LRSHIFT
;Last (X) reading
    call      RX11bit
    movf     DATAreg,0
    clrf     STATUS                    ;check if (X) or (12) entered after F0
    xorlw   0x12
    btfsc   STATUS,ZERO
    goto    BEGIN
    goto    LRSHIFT
;
CAPS                                ;caps lock (58) entered

;(F0) detection
    call      RX11bit                    ;this must be F0
    call      RX11bit                    ;this must be (58) again

CAPnext
    call      RX11bit                    ;Check if (58) or other
    clrf     STATUS
    movf     DATAreg,0
    xorlw   0x58
    btfss   STATUS,ZERO
    goto    CAPtwo                        ;End of CAP session
    call     RX11bit                       ;F0
    call     RX11bit                       ;(58)
    goto    BEGIN

                                ;a Key (X) is entered
CAPtwo
    movf     DATAreg,0

```

```

    call    CAPKeyTable
    movwf  INDF           ;store the character at INDF
    incf   FSR
    incf   Nchar
    call   LCDisplay

;(F0) detection
    call   RX11bit           ;this
    clrf   STATUS
    movf   DATAreg,0
    xorlw  0xF0
    btfss  STATUS,ZERO
    goto   CAPtwo

;Last (X) reading           ;F0 is read
    call   RX11bit           ;(X) again and ignore
    goto   CAPnext

;CR handling
CRhandle
    call   RX11bit           ;F0 read
    call   RX11bit           ;CR reading again
; text-voice conversion
    call   VoiceText
;
;read the current cursor position
    call   readad4
;DDADDR has the content
;NOTE: MSB must be 1 in the cursor command
    bsf   DDADDR, MSB
;if DDADDR<94, then new cursor position is C0
;if DDADDR<E8, then 80
;if DDADDR<C0, then D4
;if DDADDR<D4, then 94
    clrf   STATUS
    movf   DDADDR,0
    sublw  0x94           ;k-W -->W
    btfsc  STATUS,Borrow ;No borrow means that k>W
    goto   CR94           ; is less than 94
    clrf   STATUS
    movf   DDADDR,0
    sublw  0xC0
    btfsc  STATUS,Borrow
    goto   CRC0

    clrf   STATUS
    movf   DDADDR,0
    sublw  0xD4
    btfsc  STATUS,Borrow
    goto   CRD4

    clrf   STATUS
    movf   DDADDR,0
    sublw  0xE8
    btfsc  STATUS,Borrow

```

```

        goto      CRE8
        goto      BEGIN

CR94   call      posline12
        goto      begin

CRC0   call      posline14
        goto      BEGIN

CRD4   call      posline13
        goto      BEGIN

CRE8   call      LCDclearhome           ;clear screen first
        call      posline11
        goto      BEGIN

;CRE8 call      posline11
;      goto      BEGIN

;BS Handling
BShandle
        movf     DATAreg,0           ;W holds $66
        call     RX11bit              ;F0 read
        call     RX11bit              ;BS break code
;read the current cursor position
        call     readad4
;DDADDR has the content
; SO move the current to the left
;NOTE: MSB must be 1 for commanding of the cursor position
        bsf     DDADDR, MSB
;if DDADDR = 94, then new cursor position is D3
;if DDADDR = C0, then new position is 93
;if DDADDR = D4, then new position is A7
;if DDADDR = 80, then new position is 80 (NO CHANGE)
; all other cases, new position is (DDADDR - 1)
        clrf    STATUS
        movf    DDADDR,0
        xorlw   0x94
        btfsc  STATUS, ZERO
        goto   DD94
        clrf    STATUS
        movf    DDADDR,0
        xorlw   0xC0
        btfsc  STATUS, ZERO
        goto   DDC0
        clrf    STATUS
        movf    DDADDR,0
        xorlw   0xD4
        btfsc  STATUS, ZERO
        goto   DDD4
        clrf    STATUS
        movf    DDADDR,0
        xorlw   0x80
        btfsc  STATUS, ZERO
        goto   DD80
;all others

```

```

        decf      DDADDR
        decf      CURSOR
        movf     DDADDR,0
        call     instw4
        decf      FSR
        decf      Nchar
        goto     BEGIN

DD94   movlw    0xD3
        decf      CURSOR
        call     instw4
        decf      FSR
        decf      Nchar
        goto     BEGIN

DDC0   movlw    0x93
        decf      CURSOR
        call     instw4
        decf      FSR
        decf      Nchar
        goto     BEGIN

DDD4   movlw    0xA7
        decf      CURSOR
        call     instw4
        decf      FSR
        decf      Nchar
        goto     BEGIN

DD80   movlw    0x80
        call     instw4
        decf      FSR
        decf      Nchar
        goto     BEGIN

;

;=====
;SUBROUTINE LCD4INIT
;Function for 4-bit (only one write must be done)
;In other words, send only the high nibble
LCD4INIT
;IMPORTANT PART
        movlw    0x28
        call     hnibble4
;Function for 4-bit, 2-line display, and 5x8 dot matrix
        movlw    0x28
        call     instw4
;Display On, CURsor On, No blinking
        movlw    0x0E      ;0F would blink
        call     instw4
;DDRAM address increment by one & cursor shift to right
        movlw    0x06
        call     instw4
;DISPLAY CLEAR
CLEAR

```

```

        movlw    0x01
        call    instw4
;
        call    posline11          ;pos1 and line 1
;now CURSOR=1
        return
;=====

;LCD DISPLAYING SUBROUTINE
LCDisplay

        call    dataw4
        incf    CURSOR              ;every time of display, increase cursor
;CURSOR is automatically incremented by 1 from LCDisplay
;if CURSOR is 20 (0x14), change to posline12
;if CURSOR is 40 (0x28), change to posline13
;if CURSOR is 60 (0x3C), change to posline14
;if CURSOR is 80 (0x50), change to posline11
        clrf    STATUS
        movf    CURSOR,0
        xorlw   0x15
        btfsc  STATUS, ZERO
        goto    Toline2

        clrf    STATUS
        movf    CURSOR,0
        xorlw   0x29
        btfsc  STATUS, ZERO
        goto    Toline3

        clrf    STATUS
        movf    CURSOR,0
        xorlw   0x3D
        btfsc  STATUS, ZERO
        goto    Toline4

        clrf    STATUS
        movf    CURSOR,0
        xorlw   0x51
        btfsc  STATUS, ZERO
        call    LCDclearhome        ;delete all and move to (1,1)
        return

Toline2
        call    posline12
        return
Toline3
        call    posline13
        return
Toline4
        call    posline14
        return

;SUBROUTINE
;DISPLAY CLEAR and Cursor to Home position (line 1, position 1)
LCDclearhome
        movlw   0x01

```

```

        call        instw4
;Now let's move the cursor to the home position (position 1 of line #1)
;and set the DDRAM address to 0. This is done by the "return home"
instruction.

        movlw      0x02
        call        instw4
;home position
        movlw      0x80
        call        instw4
        movlw      0x01
        movwf      CURSOR
        return

;====SUBROUTINES =====
posline11
;Position to pos 1 and line 1
        movlw      0x80
        call        instw4
        movlw      0x01
        movwf      CURSOR
        return

posline12          ;pos 1 and line 2
        movlw      0xC0
        call        instw4
        movlw      0x15 ;21
        movwf      CURSOR
        return

posline13          ;pos1 and line3
        movlw      0x94
        call        instw4
        movlw      0x29 ;41
        movwf      CURSOR
        return

posline14          ;pos 1 and line 4
        movlw      0xD4
        call        instw4
        movlw      0x3D ;61
        movwf      CURSOR
        return

;
;high nibble only write for the first step of 4-bit set up
hnibble4
        movwf      Temp          ;Temp storage
        movf      Temp,0          ;Now W also holds the data
        andlw     0xF0          ; get upper nibble
        movwf     PORTB         ; send data to lcd
        call      delay1ms
        bcf      PORTB, RS
        call      delay1ms
        bsf      PORTB, E
        call      delay1ms
        bcf      PORTB, E

```

```

        call        delay10ms        ;end of high nibble for 4-bit setup
        return
;
;subroutine instw (4-bit interface instruction write)
;instruction to be written is stored in W before the call
instw4
        movwf      Temp              ;Temp storage
        movf       Temp,0            ;Now W also holds the data
        andlw     0xF0              ; get upper nibble
        movwf     PORTB              ; send data to lcd
        call      delay1ms
        bcf       PORTB, RS
        call      delay1ms
        bsf       PORTB, E
        call      delay1ms
        bcf       PORTB, E
        call      delay10ms         ;end of higher nibble
        swapf     Temp,0            ;get lower nibble to W
        andlw     0xF0
        movwf     PORTB              ;Write to LCD
        call      delay1ms
        bcf       PORTB, RS
        call      delay1ms
        bsf       PORTB, E
        call      delay1ms
        bcf       PORTB, E         ;end of lower nibble
        call      delay10ms
        return

;subroutine dataw (4-bit interface data write)
dataw4
        movwf     Temp              ;Temp storage
        movf      Temp,0            ;Now W also holds the data
        andlw     0xF0              ; get upper nibble
        movwf     PORTB              ; send data to lcd
        call      delay1ms
        bsf       PORTB, RS
        call      delay1ms
        bsf       PORTB, E
        call      delay1ms
        bcf       PORTB, E
        call      delay10ms         ;end of higher nibble
        swapf     Temp,0            ;get lower nibble to W
        andlw     0xF0
        movwf     PORTB              ;Write to LCD
        call      delay1ms
        bsf       PORTB, RS
        call      delay1ms
        bsf       PORTB, E
        call      delay1ms
        bcf       PORTB, E         ;end of lower nibble
        call      delay10ms
        return
;
;subroutine reading the cursor position
;RW Must be High

```

```

;RS Must be Low
;the 7th bit is BF flag (so ignore this one, or make MSB 0)
;PORTB <7:4> as inputs
;High then Low nibbles of ADDRESS
;The content of DDADDR read from LCD module (HEX Numbers)
;Line 1: 00 01 02 ..... 13
;Line 2: 40 41 42 ..... 53
;Line 3: 14 15 16 ..... 27
;Line 4: 54 55 56 ..... 67

```

```

readad4
    banksel    TRISB        ;set Rb7 - DR4 as inputs
    movlw     0xF0         ;upper 4 bits as inputs
    movwf    TRISB
    banksel    PORTB
    bsf       PORTB, RW    ;READING MODE
    call     delay1ms
    bcf       PORTB,RS
    call     delay1ms
    bsf       PORTB, E
    call     delay1ms
    bcf       PORTB, E     ;Reading starts here now
                                ;upper byte first

    movlw     0xF0
    andwf    PORTB,0
    movwf    DDtemp1

    bcf       PORTB,RS
    call     delay1ms
    bsf       PORTB, E
    call     delay1ms
    bcf       PORTB, E
                                ;reading starts now
                                ;for lower byte

    movlw     0xF0
    andwf    PORTB,0
    movwf    DDtemp2
    swapf    DDtemp2

;add DDtemp1 and DDtemp2 for DDADDR
;
    movf     DDtemp1,0
    addwf    DDtemp2,0
    movwf    DDADDR        ;The DD Ram ADDRESS

    banksel    TRISB
    movlw     0x00
    movwf    TRISB        ;all outputs again
    banksel    PORTB
    bcf       PORTB,RW    ;back to writing mode
    return

;=====
;subroutine
VoiceText
;if Nchar=0 return (nothing to display)

```

```

        movlw    CTRLA
        call    TXSW
        movlw    'T'
        call    TXSW        ;text mode

        banksel Nchar
        movf    Nchar,0
        clrf    STATUS
        xorlw   0x00
        btfsc  STATUS,ZERO
        return
        movlw   0xA0
        movwf   FSR
NextChar
        movf    INDF,0
        call    TXSW
        decfsz  Nchar
        goto    domore
        movlw   0x0D        ;voice triggered
        call    TXSW
        movlw   0xA0
        movwf   FSR
        return
D0more
        incf    FSR
        goto    NextChar

;=====
;DELAY SUBROUTINES

Delay120us
        banksel Kount120us
        movlw   H'C5'        ;D'197'
        movwf   Kount120us
R120us
        decfsz  Kount120us
        goto    R120us
        return
;
Delay100us
        banksel Kount100us
        movlw   H'A4'
        movwf   Kount100us
R100us
        decfsz  Kount100us
        goto    R100us
        return
;
;1ms delay
Delay1ms
        banksel Kount1ms
        movlw   0x0A        ;10
        movwf   Kount1ms
R1ms
        call    delay100us
        decfsz  Kount1ms
        goto    R1ms
        return

```

```

;
;10ms delay
; call 100 times of 100 us delay (with some time discrepancy)
Delay10ms
    banksel    Kount10ms
    movlw     H'64' ;100
    movwf     Kount10ms
R10ms call    delay100us
    decfsz    Kount10ms
    goto     R10ms
    return
;
;
;1 sec delay
;call 100 times of 10ms delay
Delay1s
    banksel    Kount1s
    movlw     H'64'
    movwf     Kount1s
R1s   call    Delay10ms
    decfsz    Kount1s
    goto     R1s
    return
;
;
;SUBROUTINE RX11bit
;RX Routine for 11-bit read
;1 Start
;8 Data (LSB first)
;1 Parity (Odd)
;1 Stop (HIGH)
;KSTAT Bit Info
; KSTAT<0> : parity
; KSTAT<2>:kBD Error
RX11bit
    clrf      DATAreg
    banksel   PORTD
;Let it have at least 500us CLOCK high period
    btfss    PORTD, CLOCK
    goto     RX11bit ;if CLOCK is LOW, start again
    call     Delay100us ;200uS delays
    call     Delay100us
;check again for CLCOK
    btfss    PORTD, CLOCK
    goto     RX11bit
;Clock Check
Scheck
    btfsc    PORTD,CLOCK
    goto     Scheck
    call     delay5us ;wait for 5us for data stabilization
    btfsc    PORTD, KDATA
    goto     KERROR ;if START BIT is not Zero ERROR
;START Detected
;8-bit Data Check
    movlw    0x08

```

```

        movwf    Bitcount    ;8 data bits
RXNEXT
        bcf     STATUS, CARRY    ;Clear the Carry Bit
        rrf     DATAreg        ;rotate to the right
CKHIGH
        btfss   PORTD, CLOCK     ;Wait for CLOCK to back to High
        goto    CKHIGH
CKLOW  btfsc   PORTD, CLOCK     ;wait for CLOCK now to LOW
        goto    CKLOW
        call    delay5us        ;5us delay
        btfsc   PORTD, KDATA     ;0 or 1
        bsf     DATAreg, MSB    ;1? Then set the MSB
        decfsz  Bitcount
        goto    RXNEXT
;Check for Parity Bit
;Wait for CLOCK bacj to High
CKHIGH2
        btfss   PORTD, CLOCK     ;Wait for CLOCK to back to High
        goto    CKHIGH2
CKLOW2
        btfsc   PORTD, CLOCK     ;wait for CLOCK now to LOW
        goto    CKLOW2
        call    delay5us        ;5us delay
        btfsc   PORTD, KDATA     ;Parity Bit
        goto    OneP            ;Pbit=1
        bcf     Kstat, 0x00      ;Pbit=0
        goto    Stopcheck
OneP   bsf     Kstat, 0x00      ;Pbit=1
Stopcheck
;wait for CLOCK back to High
CKHIGH3
        btfss   PORTD, CLOCK     ;Wait for CLOCK to back to High
        goto    CKHIGH3
CKLOW3
        btfsc   PORTD, CLOCK     ;wait for CLOCK now to LOW
        goto    CKLOW3
        call    delay5us        ;5us delay
        btfss   PORTD, KDATA     ;STOP bit
        goto    KERROR          ;if STOP=0 , ERROR
        return
KERROR
        bsf     KSTAT, 0x02
        return
;=====
;Software TX routine for RC8650
;The data to be sent is stored in W
TXSW
        banksel RCSreg
        movwf   RCSreg
        movlw   0x08            ;8 ---->W
        movwf   Bitcount       ;8 data bits

;send a START bit
        bcf     PORTD, TXPin
;delay for 1*(BC) cycles
        call    Delay52us      ;Keep this!
TXNEXT

```

```

        bcf          STATUS, CARRY
        rrf          RCSreg          ;LSB first mode (normal)
        btfsc       STATUS,CARRY
        bsf         PORTD, TXPin
        btfss       STATUS,CARRY
        bcf         PORTD, TXPin
        call        Delay52us        ;KEEP THIS!
        decfsz      Bitcount
        goto        TXNEXT
;send STOP bit
        bsf         PORTD, TXPin
        call        Delay52us        ;keep tHIS!
;wait until the end of STOP bit
        return

```

```

delay5us
;need total 10 instructions
        nop
        return

```

```

;delay 52us for one baud cycle of 19200 bps

```

```

Delay52us
        movlw      0x54
        movwf      Kount52us
R52us  decfsz      Kount52us
        goto       R52us
        return

```

```

;100ms delay

```

```

Delay100ms
        banksel    Kount100ms
        movlw      0x0A ;10
        movwf      Kount100ms
R100ms call        delay10ms
        decfsz     Kount100ms
        goto       R100ms
        return

```

```

;
Delay500ms
        call       delay100ms
        call       delay100ms
        call       delay100ms
        call       delay100ms
        call       delay100ms

```



```

retlw 0
DT  "ZSAW@"      ;+1A, 1B, 1C, 1D, 1E
retlw 0      ;+1F
retlw 0      ;+20
DT  "CXDE$#"    ;+21, 22, 23, 24, 25, 26
retlw 0      ;+27
retlw 0      ;+28
retlw ' '     ;+29 Space
DT  "VFTR%"    ;+2A, 2B, 2C, 2D, 2E
retlw 0      ;+2F
retlw 0      ;+30
DT  "NBHGY^"   ;+31, 32, 33, 34,35,36
retlw 0      ;+37
retlw 0      ;+38
retlw 0      ;+39
DT  "MJU&*"    ;+3A, 3B, 3C, 3D, 3E
retlw 0      ;+3F
retlw 0      ;+40
DT  "<KIO)("    ;+41, 42,43,44,45,46
retlw 0      ;+47
retlw 0      ;+48
DT  ">?L:P_"   ;+49, 4A, 4B, 4C, 4D, 4E
retlw 0      ;+4F
retlw 0      ;+50
retlw 0      ;+51
retlw 0x22   ;+52 double quote
retlw 0      ;+53
DT  "{+"      ;+54, 55
retlw 0      ;+56
retlw 0      ;+57
retlw 0      ;+58
retlw 0      ;+59
retlw 0x0D   ;+5A Return
retlw '}'    ;+5B
retlw 0      ;+5C
retlw 0x7C   ;+5D |
retlw 0      ;+5E
retlw 0      ;+5F
retlw 0      ;+60
retlw 0      ;+61
retlw 0      ;+62
retlw 0      ;+63
retlw 0      ;+64
retlw 0      ;+65
retlw 0x08   ;+66 Backspace

;CAPs Lock Key Table
org          0x0400
CAPKeyTable
bsf         PCLATH, 0x02
bcf         PCLATH, 0x01
bcf         PCLATH, 0x00
addwf      PCL
retlw 0     ;PC+0
retlw 0     ;PC+1
retlw 0     ;+2
retlw 0

```



```
    retlw 0      ;+5F
    retlw 0      ;+60
    retlw 0      ;+61
    retlw 0      ;+62
    retlw 0      ;+63
    retlw 0      ;+64
    retlw 0      ;+65
    retlw 0x08   ;+66  Backspace

;END OF CODE
    END
```

I hope you have enough patience to learn about this new board and coding for 16F877 chip.