The Terminator arm



Brief Introduction of the Proposed Project

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Objective



 Design an inexpensive, non-invasive prosthetic arm controlled by electrical pulses from the brain

Motivation

- Cost: Traditional myoelectric prosthetics cost upwards of \$3000, this would be assembled for less than one-tenth the price
- Functionality: e-NABLE has open-sourced design for hand-prosthetics that are purely mechanical "Inexpensive & electrically activated prosthetics are rare"

Limited Functionality of current Inexpensive hand Prosthetics



Attributes

- Successfully mimic basic hand gestures including finger position (i.e contraction/relaxation) & fist clench/Palm spread
- Prosthetic should be heat-sensitive
- Provide a "pathway" to development of inexpensive & highly functional prosthetic arms. Also, provides a great design experience for students

What's involved?

EE: Motors, wires, current, sensors, alert



 CpE: Microcontroller, Programming, SDK/Interface for electromyographic sensor

ME: 3D printing

Proposed plans

- Assemble "Power" team of 8
 - Faculty (Prof. Anderson)
 - Graduate student (Ang Yu)
 - EE/CpE seniors (2 EE / 1CpE)
 - 1 ME student
 - 1 Underclassman
- Build Terminator arm
- Demo (Projections)
- Multi gesture, grip
- Catch a flying ball
- Respond to hot object



Preliminary Outline (Susceptible to change)

- Team size?
- Demo specifics?
- Bring your ideas!
- •Let me know if you're interested!

It's not going to be easy, but of course! we're Engineers!...