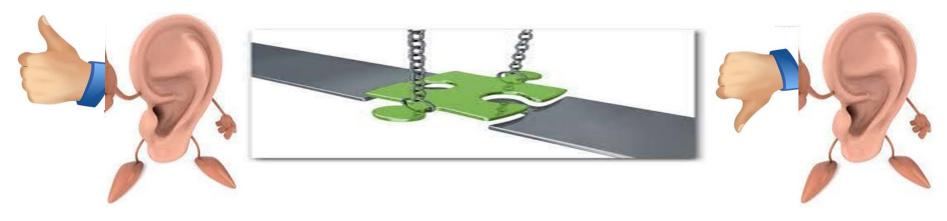
Electrical and Computer Engineering Howard University

EECE401 Senior Design I Dr. Charles Kim -- Instructor WWW.MWFTR.COM/SD1415.html

#### Sign Language to English



#### Team SLatE8

Reginald Etienne, Marcos Celestino Carvalho Junior, Sarad Dhungel, Renika Montgomery, Claude Ndzami, Yonatan Yilma.

> Prajjwal Dangal, Roshil Paudyal

## Background

#### Customer:

- Hearing Impaired community in the U.S. (28 million)
- Parents of hearing impaired children
- business
- office
- retail
- ect.



## Background

#### Needs and Demand:

- portable device
- easy to use
- fast response time and accuracy
- long battery life
- helpful
- fastest communication
- ect.



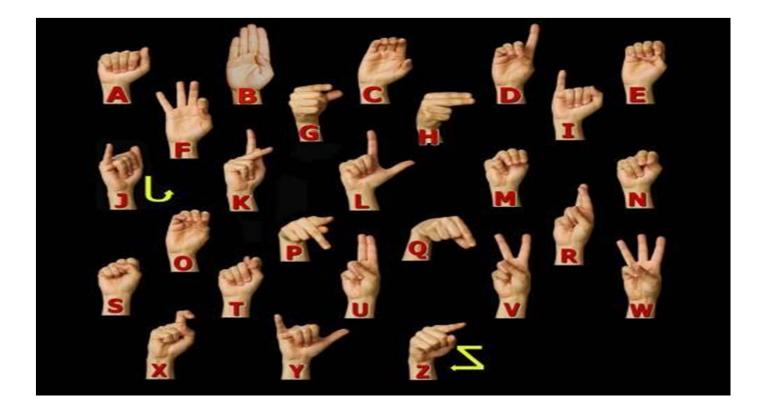




#### **Problem Statement**

The core principle of our team project is to build a device that will help to integrate the deaf/mute community more into society by developing a device able to understand, translate, and communicate with a person not knowledgeable with ASL by interpreting ASL into English.

## **Problem Statement Count'd**



## **Design Requirements**

#### Internal features: Intel Galileo Board

- ≻Physical Characteristics
- ➤Communication
- ≻Processor Features
- ➤Storage Option
- Constraints:
  - ≻Resources
  - ≻Time
  - ≻System Developments

#### **Design Requirements**

•Weight & Size: less than 15 oz, 10x5x2 in.

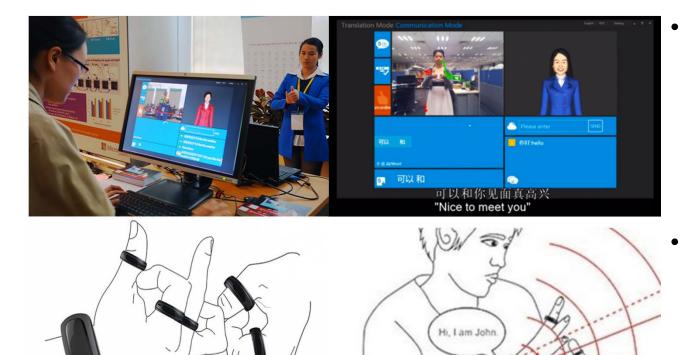
- •Camera: 640x480 bit resolution
- •Sound system: 3.5 mm TRRS, with frequency response range from 20Hz to 20kHz.
- •Display screen: touch screen about 3.5in diagonal of a resolution of 640x480 at 326 ppi (0.61megapixels) with a typical 800:1 contrast ratio.
- •Response time: no more than 30 seconds after the camera captures the picture of sign.
- •Accuracy: are greater than 90% and error are below 5%.

#### **Current Status of Art**



- MyVoice (University of Houston students of engineering technology and industrial design programs)
- EnableTalk gloves translate sign language into speech in real time (Ukraine's quadSquad winners at Microsoft Imagine Cup

#### **Current Status of Art**



Kinect Sign Language Translator (Microsoft Asia)

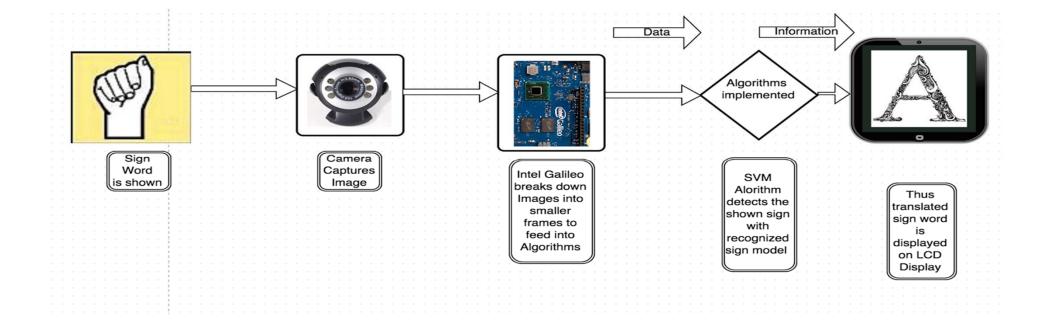
The Sign Language Ring (winner of the 2013 RedDot Design Award)

## **Solution Approach**

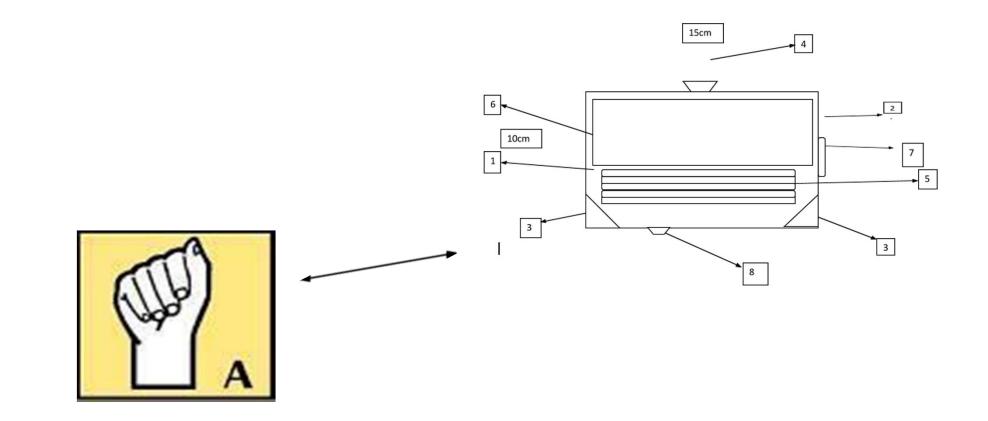
Design a working prototype which is

- Handheld and Portable
- Efficient and inexpensive means to bridge communication gap
- A fast and efficient method of communication

## **Solution Approach**



## **Conceptual Design I**



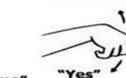
# **Conceptual Design I**

Button	Function	Description
1 – Power Button	ON/OFF	Turn the device off
2 - Speakers	To provide the output	Allows Customers to hear
3 - Camera	Captures images of Sign	Camera captures the video of users gesture and then convert into text
4 - Distance from the Object to the Camera	To read the object capture	To Test the accuracy of the device at different distance that an object is capture
5 - Keyboard	To control the volume	Customer can type in word to know the sign for the word
6 - Screen	Display	Allows Customers to see what sign will look like
7- Volume	To control the volume	To increase or decrease the volume to understand the speaker perfectly.

## **Conceptual Design II**



"Goodbye"



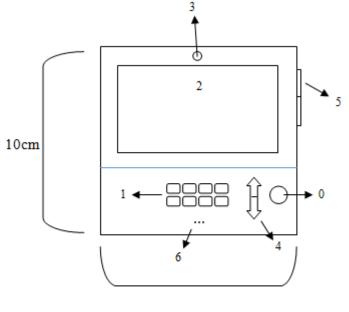
"You're Welcome"

"No"



"Sorry"

"Thanks



10cm

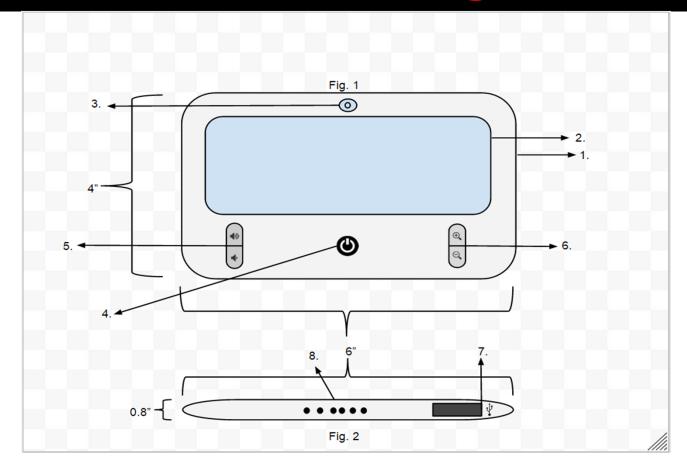
# **Conceptual Design II**

Button	Function	Description
0 - Power	ON/OFF	Turn the device off
1 - Keyboard	To input text into a computer	To help the user to enter data
2 - LCD Screen	To display image on the screen	Produces the visible image on the screen to help the user to read/identify the correct output
3 - Camera	Motion Controller	Camera captures the video of users gesture and then convert into text
4 - Distance from the Object to the Camera	To read the object capture	To Test the accuracy of the device at different distance that an object is capture
5 - Volume	To control the volume	To increase or decrease the volume to understand the speaker perfectly.
6 - Speakers	To provide the output	Responsible to present the output for the translation by sound.

## **Top Design Selection**

	Conceptual				Conceptual Design		
Attributes	Design I	Weight	Score	Agg. Score		Score	Agg. Score Analysis Method
Speed	100 Mhz/sec	5	4	20	120 Mhz/sec	5	25 Speed of Operation
Responce Time	12 sec	4	4	16	10 sec	5	20 Time in sec
Weight	15 Oz	3	5	15	17 OZ	3	9 weignt in Ibs
Power	AC conveter and USB cable	2	2	4	AC converter and DC Power Connector - 2.5mm I.D 5.5mm O.D	1.5	3 Method of charging
Life	6 Hour usage, 12 Hour Standby	2	5	10	4 Hour Usage, 10 Hour Standby	4	8 Battery Life in time
Screen Size	3.5in diagonally	4	3	12	9.7 in diagnolally	4	16 Size in inches
Screen Type	960x640 at 326 ppi	4	3.5	14	960x640 at 326 ppi	3.5	14 Resolution of screen
Camera	5-megapixel camera embedded in device	5	5	25	4megapixels camera connected Outside	4	20 Capacity in pixels
Video Capture	720p	5	5	25	.6megapixel	4	Capture capability in 20 pixel
Volume Button	2 Buttons for Volume Up and Down	2	2	4	Rotating volume control	1.5	3 Convenience
Dimension	10 X 10 X 2	5	4	20	15 X 10 X 2	5	
Display Screen	6 X 4	5	4	20	12 X 5	5	Size and quality of 25 display
Power Switch	On the the front face of the device	2	2	4	One the right edge of the device	2	4 Convenience
Total		48	48.5	189		47.5	192

## **Final Design**



# **Final Design**

Attributes	Details
Weight	15 ounces (425.5 gm)
Height	4 inch (10.16 cms)
Width	6 inch (15.24 cms)
Depth	0.8 inch (2.03 cms)
Display	2" X 4.75"X 5.15 Screen( Diagonal), 960 X 640 at 326 ppi
Camera	5.1 megapixels
Video	720p Video recording ( 30-60fps)
Power	AC converter and USB
Battery	Built in rechargeable lithium-ion battery
Speakers	On the bottom middle of the device
Buttons	1-Turn ON/OFF 2- Volume UP/DOWN 2- Zoom IN/OUT (to focus)

#### Cost & Resources- 1<sup>st</sup> prototype

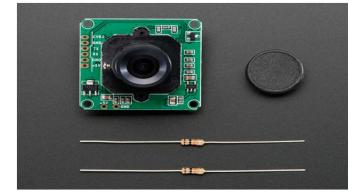


Tablet kit with a 4.4" OLED touchscreen that mounts directly on the Board **\$295** 

## Cost & Resources- 1<sup>st</sup> prototype



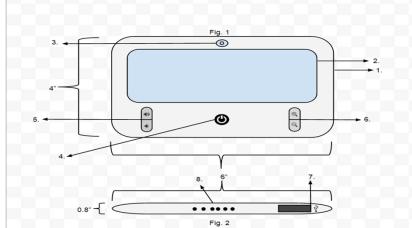


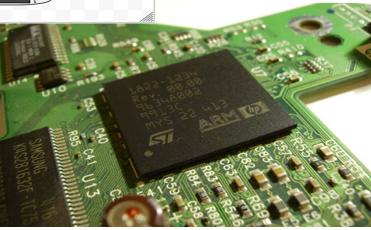




- Intel Galileo **\$60**
- TTL Serial JPEG
  Camera with NTSC
  Video \$40
- 7"inch fpc3tp70001av2 Black Glass Panel Touch Screen Digitizer \$24
- Anker® 2nd Gen Astro E4 13000mAh External Battery \$30

#### Cost & Resources- final prototype





**Goal:** Final product for customer should not cost more than **\$100**.

To fit design parameters some changes maybe required such as ARM Microcontrollers **\$45** 

Fabrication cost \$??

# Implementation and Verification Plan



## **Stage 1- Still Image Analysis**

Image Processi ng Timeline

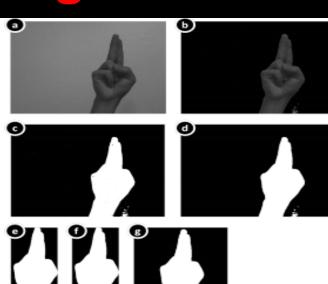


Table 1: Pixel Feature Classification Results

	C.V. accuracy		Test accuracy	
Classifier	12 signs	25 signs	12 signs	25 signs
Linear kernel	97.2%	90.8%	98.6%	92.4%
Gaussian kernel	98.3%	92.4%	98.6%	93.5%
k- nearest- neighbor	N/A	N/A	93.0%	84.8%

20x20px images

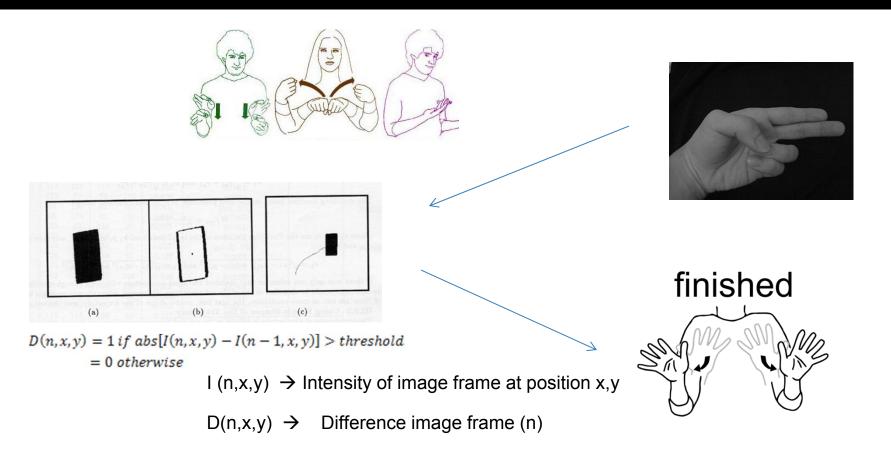
\*problem with j & z

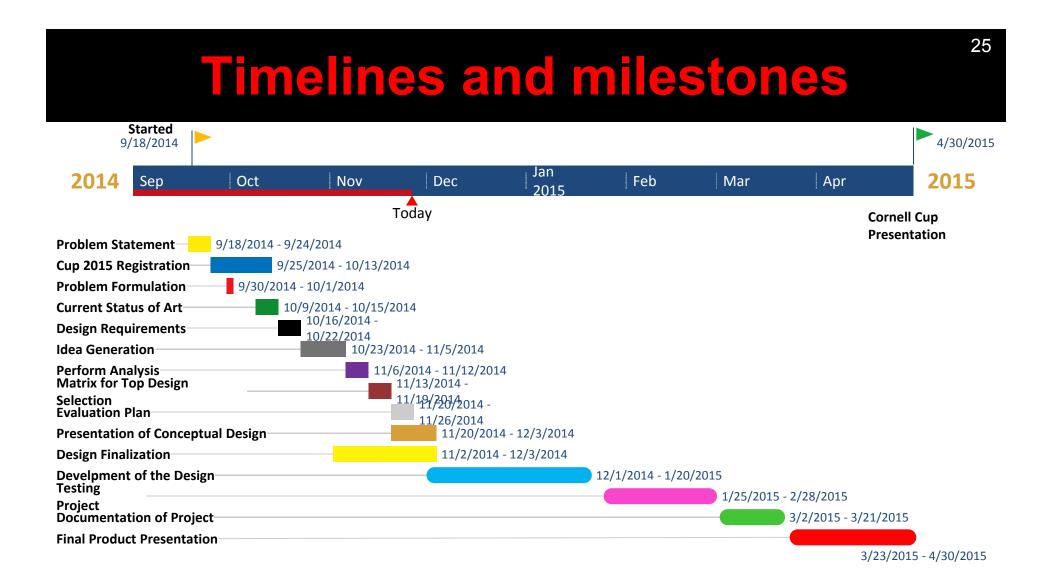
Classify using linear and Gaussian kernel SVM

Run cross-validations to determine optimal SVM parameters C and 6

- 1. Knight
- 2. Shariff
- 3. Marx
- 4. \*Markov

# **Stage 2- Image Motion Analysis**





#### Conclusion

•SLATE 8 will use all resources available to reach the goal of providing a *portable* and *cost efficient* device that can help the hearing impaired community communicate easier by translating sing language into text/voice.



## Questions

