THE BISON BOT

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A newcomer entering LKD might feel overwhelmed and disoriented due to the building's lack of clear signage and maps, making it difficult to locate classrooms and offices.



DESIGN SPECIFICATIONS





1. lidar scanner



2. manuverability





4. power management







DESIGN CONSTRAINTS

ENVIORNMENTAL

Excessive noise

Power constraint

SOCIO-CULTURAL

It's designed to be user-friendly, inclusive, and a reflection of Howard's welcoming and innovative spirit.

COMPLIANCE The safety standard for robots (ANSI)/Robotic Industries Association (RIA) R15.06-2012. FCC compliant

COMPONENT LEVEL SCHEMATIC

Drive Train Schematic

Drive Train Computer Model



Mapping and Logic Schematic



BISON BOT

SPRINT #1 Piece : Fabrication of a Digital Twin

Weekly Tasks:

Week 1: Retrieve Gazebo laptop and map floor 1

Week 2: LT simulations and proof of component compatibility

Week 3: precise wood dimensions for frame cutouts

Scatter Plot of My room



BISON BOT

SPRINT #2 Piece : Bison Bot Assembly

Weekly Tasks: Week 1: Drive train assembly and frame

Week 2: Electronic attachment of lidar, converters, battery, etc

Week 3: hardware programming



Cutting of woodframe

SPRINT #2

Demonstration of Drive Train





Wooden Frame Cutting



SPRINT #2

Drive Train





Full Frame Assembly





SPRINT #3 Piece : Testing and Debugging

Weekly Tasks:

Week 1: Navigation testing and user interface programming

Week 2: Full Bison Bot testing and debugging

Week 3: Final presentation practice



Drive train demonstration



SPRINT #3

Application of Vinyl



wooden frame attached to drivetrain



CONCLUSION





Navigate to this second floor restroom and back Display output of lidar scan (scatter plot) Continuous interactive user interface